

WELLENAUSBREITUNG

Formelsammlung

INSTITUT FÜR NACHRICHTENTECHNIK
UND HOCHFREQUENZTECHNIK

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Gregor Lasser

Maxwellsche Theorie

$$\vec{\nabla} \cdot \vec{S} = \lim_{V \rightarrow 0} \frac{1}{V} \oint_{\Sigma} \vec{S} \cdot d\vec{F} = -\frac{\partial}{\partial t} \rho$$

$$\vec{\nabla} \cdot (\vec{\nabla} \times \vec{H}) \equiv 0$$

$$\vec{\nabla} \times \vec{H} = \vec{S} + \frac{\partial}{\partial t} \vec{D}$$

$$\vec{\nabla} \cdot \vec{S} = -\frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{D}) = -\frac{\partial}{\partial t} \rho$$

$$\vec{\nabla} \cdot \vec{S} + \frac{\partial}{\partial t} \rho = 0$$

$$\vec{\nabla} \cdot \vec{D} = \rho$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial}{\partial t} \vec{B}$$

$$\vec{\nabla} \times \vec{H} = \vec{S} + \frac{\partial}{\partial t} \vec{D}$$

$$\int_{\Sigma} \vec{D} \cdot d\vec{F} = \int_{\tau} \rho dV$$

$$\int_{\Sigma} \vec{B} \cdot d\vec{F} = 0$$

$$\oint \vec{E} \cdot d\vec{l} = -\frac{\partial}{\partial t} \int_{\Sigma} \vec{B} \cdot d\vec{F}$$

$$\oint \vec{H} \cdot d\vec{l} = \int_{\Sigma} \vec{S} \cdot d\vec{F} + \frac{\partial}{\partial t} \int_{\Sigma} \vec{D} \cdot d\vec{F}$$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

$$\vec{S} = \sigma \vec{E}$$

$$\vec{S} = \rho \vec{v}$$

$$\vec{D} = \epsilon \vec{E} = \epsilon_r \epsilon_0 \vec{E}$$

$$\vec{B} = \mu \vec{H} = \mu_r \mu_0 \vec{H}$$

$$\frac{\partial}{\partial t} \rho(\vec{r}, t) + \frac{\sigma}{\epsilon} \rho(\vec{r}, t) = 0$$

$$\rho(\vec{r}, t) = \rho_0(\vec{r}) e^{-\frac{\sigma}{\epsilon} t}$$

$$\tau_D = \frac{\epsilon}{\sigma}$$

$$\vec{\nabla} \cdot \vec{E} = 0$$

$$\vec{E}(x, y, z, t) = \vec{E}(\vec{r}, t) = \text{Re}\{\vec{E}(\vec{r}) e^{j\omega t}\} = \frac{1}{2} \left(\vec{E}(\vec{r}) e^{j\omega t} + \vec{E}^*(\vec{r}) e^{-j\omega t} \right)$$

$$\vec{\nabla} \times \vec{H} = \vec{S} + j\omega \vec{D} = \sigma \vec{E} + j\omega \epsilon \vec{E} = j\omega \delta \vec{E}$$

$$\delta = \epsilon + \frac{\sigma}{j\omega} = \epsilon - j \frac{\sigma}{\omega}$$

$$\tan \theta = \frac{\epsilon''}{\epsilon'} = \frac{\sigma}{\omega \epsilon}$$

$$\vec{\nabla} \cdot \vec{E} = 0$$

$$\vec{\nabla} \cdot \vec{H} = 0$$

$$\vec{\nabla} \times \vec{E} = -j\omega \mu \vec{H}$$

$$\vec{\nabla} \times \vec{H} = j\omega \delta \vec{E}$$

$$\vec{P}(t) = \vec{E}(t) \times \vec{H}(t)$$

$$\vec{\nabla} \cdot \vec{P}(t) = -\sigma \underbrace{\vec{E}(t) \cdot \vec{E}(t)}_{\vec{E}^2(t)} - \frac{\partial}{\partial t} \left(\frac{\epsilon}{2} \underbrace{\vec{E}(t) \cdot \vec{E}(t)}_{\vec{E}^2(t)} + \frac{\mu}{2} \underbrace{\vec{H}(t) \cdot \vec{H}(t)}_{\vec{H}^2(t)} \right)$$

$$w_e(t) = \frac{\epsilon}{2} \vec{E}^2(t)$$

$$w_m(t) = \frac{\mu}{2} \vec{H}^2(t)$$

$$p_v(t) = \sigma \vec{E}^2(t)$$

$$\int_{\mathcal{V}} \vec{\nabla} \cdot \vec{P}(t) dV = \oint_{\Sigma} \vec{P}(t) \cdot d\vec{F}$$

$$-\frac{\partial}{\partial t} \int_{\mathcal{V}} (w_e(t) + w_m(t)) dV = \oint_{\Sigma} \vec{P}(t) \cdot d\vec{F} + \int_{\mathcal{V}} p_v(t) dV$$

$$\vec{E}(\vec{r}, t) = \frac{1}{2} \left(\vec{E}(\vec{r}) e^{j\omega t} + \vec{E}^*(\vec{r}) e^{-j\omega t} \right)$$

$$\vec{E}(t) \cdot \vec{E}(t) = \frac{1}{4} \left(\vec{E}(\vec{r}) \cdot \vec{E}(\vec{r}) e^{2j\omega t} + 2\vec{E}(\vec{r}) \cdot \vec{E}^*(\vec{r}) + \vec{E}^*(\vec{r}) \cdot \vec{E}^*(\vec{r}) e^{-2j\omega t} \right)$$

$$\overline{\vec{E}(t) \cdot \vec{E}(t)} = \frac{1}{2} |\vec{E}(t)|^2$$

$$\overline{w_e(t)} = w_e = \frac{\epsilon}{4} |\vec{E}(t)|^2$$

$$\overline{w_m(t)} = w_m = \frac{\mu}{4} |\vec{H}(t)|^2$$

$$\overline{p_v(t)} = p_v = \frac{\sigma}{2} |\vec{E}(t)|^2$$

$$\vec{T} = \frac{1}{2} \vec{E} \times \vec{H}^* = \vec{T}_w + j\vec{T}_b$$

$$\begin{aligned}
\oint \vec{E} \cdot d\vec{l} &= E_{t1}\Delta l + E_{n1}\Delta x + E_{n2}\Delta x - E_{t2}\Delta l - E_{n2}\Delta x - E_{n1}\Delta x \\
&= (E_{t1} - E_{t2})\Delta l - 0E_{n1} + 0E_{n2} = -\frac{\partial}{\partial t} \int_F \vec{B} \cdot d\vec{F} = 0
\end{aligned}$$

$$E_{t1} = E_{t2}$$

$$H_{t1} = H_{t2}$$

$$\int \vec{D} \cdot d\vec{F} = (D_{n1} - D_{n2})\Delta F = \rho_S \Delta F$$

$$D_{n1} - D_{n2} = \rho_S \quad \rightarrow \quad \varepsilon_1 E_{n1} - \varepsilon_2 E_{n2} = \rho_S$$

$$B_{n1} = B_{n2} \quad \rightarrow \quad \mu_1 H_{n1} = \mu_2 H_{n2}$$

$$\vec{n} \cdot \vec{D}_1 = \rho_S$$

$$\vec{n} \cdot \vec{B}_1 = 0$$

$$\vec{n} \times \vec{E}_1 = \vec{0}$$

$$\vec{n} \times \vec{H}_1 = \vec{K}$$

$$\vec{n} \cdot (\vec{D}_1 - \vec{D}_2) = \rho_S$$

$$\vec{n} \cdot (\vec{B}_1 - \vec{B}_2) = 0$$

$$\vec{n} \times (\vec{E}_1 - \vec{E}_2) = \vec{0}$$

$$\vec{n} \times (\vec{H}_1 - \vec{H}_2) = \vec{K}$$

$$\nabla^2 \vec{E} - \mu\varepsilon \frac{\partial^2}{\partial t^2} \vec{E} - \mu\sigma \frac{\partial}{\partial t} \vec{E} = 0$$

$$\nabla^2 \vec{E} + (\omega^2 \mu\varepsilon - j\omega\mu\sigma) \vec{E} = 0$$

$$\nabla^2 \vec{E} + \omega^2 \mu\delta \vec{E} = 0$$

$$\nabla^2 \vec{H} + \omega^2 \mu\delta \vec{H} = 0$$

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

$$k = \omega\sqrt{\mu\delta}$$

$$\Psi(x, y, z) = X(x) Y(y) Z(z)$$

$$\frac{1}{X(x)} \frac{\partial^2}{\partial x^2} X(x) + \frac{1}{Y(y)} \frac{\partial^2}{\partial y^2} Y(y) + \frac{1}{Z(z)} \frac{\partial^2}{\partial z^2} Z(z) + \underbrace{k^2}_{\text{const.}} = 0$$

$$\frac{1}{X(x)} \frac{\partial^2}{\partial x^2} X(x) = -k_x^2$$

$$k_x^2 + k_y^2 + k_z^2 = k^2 = \omega^2 \mu\delta$$

$$\frac{\partial^2}{\partial x^2} X(x) + k_x^2 X(x) = 0$$

$$\begin{aligned}
\frac{\partial}{\partial y}H_z - \frac{\partial}{\partial z}H_y &= j\omega\delta E_x \\
\frac{\partial}{\partial z}H_x - \frac{\partial}{\partial x}H_z &= j\omega\delta E_y \\
\frac{\partial}{\partial x}H_y - \frac{\partial}{\partial y}H_x &= j\omega\delta E_z \\
\frac{\partial}{\partial y}E_z - \frac{\partial}{\partial z}E_y &= -j\omega\mu H_x \\
\frac{\partial}{\partial z}E_x - \frac{\partial}{\partial x}E_z &= -j\omega\mu H_y \\
\frac{\partial}{\partial x}E_y - \frac{\partial}{\partial y}E_x &= -j\omega\mu H_z
\end{aligned}$$

$$\begin{aligned}
E_x &= \frac{-j}{\kappa^2} \left(k_z \frac{\partial}{\partial x} E_z + \omega\mu \frac{\partial}{\partial y} H_z \right) \\
E_y &= \frac{-j}{\kappa^2} \left(k_z \frac{\partial}{\partial y} E_z - \omega\mu \frac{\partial}{\partial x} H_z \right) \\
H_x &= \frac{-j}{\kappa^2} \left(k_z \frac{\partial}{\partial x} H_z - \omega\delta \frac{\partial}{\partial y} E_z \right) \\
H_y &= \frac{-j}{\kappa^2} \left(k_z \frac{\partial}{\partial y} H_z + \omega\delta \frac{\partial}{\partial x} E_z \right)
\end{aligned}$$

Die homogene ebene Welle (HEW)

$$+\frac{\partial}{\partial z}e_y = \mu \frac{\partial}{\partial t}h_x$$

$$-\frac{\partial}{\partial z}e_x = \mu \frac{\partial}{\partial t}h_y$$

$$0 = \mu \frac{\partial}{\partial t}h_z$$

$$-\frac{\partial}{\partial z}h_y = \varepsilon \frac{\partial}{\partial t}e_x$$

$$+\frac{\partial}{\partial z}h_x = \varepsilon \frac{\partial}{\partial t}e_y$$

$$0 = \varepsilon \frac{\partial}{\partial t}e_z$$

$$\frac{\partial^2}{\partial z^2}e_x - \mu\varepsilon \frac{\partial^2}{\partial t^2}e_x = 0$$

$$e_x(z, t) = \underbrace{c_1 f_1(z - vt)}_{=e_x^+(z, t)} + \underbrace{c_2 f_2(z + vt)}_{=e_x^-(z, t)}$$

$$v = \frac{1}{\sqrt{\varepsilon\mu}} = \frac{\omega}{k}$$

$$\eta = \sqrt{\frac{\mu}{\varepsilon}}$$

$$\eta = \eta_0 = \sqrt{\frac{\mu_0}{\varepsilon_0}} \approx 120\pi\Omega \approx 377\Omega$$

$$h_x^+ = -\frac{e_y^+}{\eta}$$

$$\frac{e_x^+}{h_y^+} = -\frac{e_y^+}{h_x^+} = \eta$$

$$\vec{E} \perp \vec{H} \perp \vec{i}_z$$

$$\frac{e_x^-}{h_y^-} = -\frac{e_y^-}{h_x^-} = -\eta$$

$$w_e(t) = \frac{\varepsilon}{2}(e_x^2 + e_y^2)$$

$$w_m(t) = \frac{\mu}{2}(h_x^2 + h_y^2)$$

$$w_m(t) = \frac{\mu}{2} \frac{1}{\eta^2} (e_x^2 + e_y^2) = w_e(t)$$

$$p_x^+ \equiv 0$$

$$p_y^+ \equiv 0$$

$$p_z^+ = e_x^+ h_y^+ - e_y^+ h_x^+$$

$$p_z^+ = \frac{1}{\eta} (e_x^{+2} + e_y^{+2})$$

$$\overline{\vec{P}(t)} = \overline{\vec{E} \times \vec{H}} = \frac{1}{\eta} \left(\overline{e_x^{+2} + e_y^{+2}} \right) \vec{i}_z = \frac{1}{2\eta} \left(\overline{E_{x0}^2 + E_{y0}^2} \right) \vec{i}_z$$

$$e_x(z, t) = \text{Re}\{E_x(z) e^{j\omega t}\} = E_0 \cos(kvt - z) = E_0 \cos(\omega t - kz)$$

$$k = \frac{\omega}{v} = \omega \sqrt{\mu \epsilon}$$

$$\lambda = \frac{2\pi}{k} = \frac{2\pi}{\omega \sqrt{\epsilon \mu}}$$

$$\vec{E}_1 = \vec{E}_x = (E_1 \vec{i}_x + 0 \vec{i}_y) e^{-jkz}$$

$$\vec{E}_2 = \vec{E}_y = (0 \vec{i}_x + E_2 \vec{i}_y) e^{-jkz}$$

$$e_x(z, t) = E_1 \cos(\omega t - kz)$$

$$e_y(z, t) = E_2 \cos(\omega t - kz + \psi)$$

$$e_x(0, t) = E_1 \cos(\omega t)$$

$$e_y(0, t) = E_2 \cos(\omega t + \psi)$$

$$e_x(0, t) = E \cos(\omega t),$$

$$e_y(0, t) = E \cos\left(\omega t \mp \frac{\pi}{2}\right) = \pm E \sin(\omega t)$$

$$e_x(z, 0) = E \cos(-kz) = E \cos(kz)$$

$$e_y(z, 0) = E \cos\left(-kz \pm \frac{\pi}{2}\right) = \pm E \sin(kz)$$

$$\vec{E} = E_{y0} e^{-jkz} \vec{i}_y$$

$$\eta \vec{H} = -E_{y0} e^{-jkz} \vec{i}_x$$

$$P = \int \vec{P} \cdot d\vec{F} = \frac{1}{2} \text{Re}\left\{ \int (\vec{E} \times \vec{H}^*) \cdot d\vec{F} \right\}$$

$$= \frac{1}{2} \text{Re}\left\{ \int (E_x H_y^* - E_y H_x^*) dF \right\}$$

$$= \frac{wd}{2} \text{Re}\left\{ -E_{y0} e^{-jkz} \left(-\frac{E_{y0}}{\eta} e^{+jkz} \right) \right\} = \frac{E_{y0}^2}{2\eta} wd$$

$$P = \frac{|U|^2}{2Z_{PV}}$$

$$U = \int_{-d}^0 E_y dy = E_{y0} d$$

$$P = \frac{|E_{y0}|^2 d^2}{2Z_{PV}}$$

$$\vec{\nabla} \times \vec{E} = -j\omega\mu\vec{H}$$

$$\vec{\nabla} \times \vec{H} = \sigma\vec{E} + j\omega\varepsilon\vec{E}$$

$$\delta = \varepsilon - j\frac{\sigma}{\omega} = \varepsilon(1 - js)$$

$$s = \frac{1}{Q} = \tan\theta = \frac{\sigma}{\varepsilon\omega}$$

$$\eta^2 = \frac{\mu}{\delta} = \frac{\mu}{\varepsilon} \frac{1}{1 - js}$$

$$\eta = \mathbb{R} + j\mathbb{X} = \eta_E \frac{1}{\sqrt{1 - js}}$$

$$jk_z = j\omega\sqrt{\mu\delta} = j\omega\sqrt{\mu\varepsilon}\sqrt{1 - js} = \gamma = \alpha + j\beta$$

$$jk_z = jk_E\sqrt{1 - js}$$

$$\mathbb{R} = \eta_E \sqrt{\frac{\sqrt{1 + s^2} + 1}{2(1 + s^2)}} \quad \mathbb{X} = \eta_E \sqrt{\frac{\sqrt{1 + s^2} - 1}{2(1 + s^2)}}$$

$$\alpha = k_E \sqrt{\frac{\sqrt{1 + s^2} - 1}{2}} \quad \beta = k_E \sqrt{\frac{\sqrt{1 + s^2} + 1}{2}}$$

$$\eta \approx \eta_E \left(1 + j\frac{s}{2}\right) \quad jk_z \approx k_E \left(\frac{s}{2} + j\right)$$

$$\eta \approx \eta_E \frac{1 + j}{\sqrt{2s}} \quad jk_z \approx k_E \sqrt{\frac{s}{2}} (1 + j)$$

$$d = \frac{1}{\alpha} \approx \frac{1}{k_E} \sqrt{\frac{2}{s}} = \sqrt{\frac{2}{\omega\mu\sigma}}$$

Reflexion an glatten Grenzflächen, die Parallelplattenleitung

$$\frac{\sin \Theta_1}{\sin \Theta_2} = \sqrt{\frac{\varepsilon_2}{\varepsilon_1}} = \frac{n_2}{n_1}$$

$$\Gamma_{\text{TM}} = \frac{\sqrt{\varepsilon_2} \cos \Theta_1 - \sqrt{\varepsilon_1} \cos \Theta_2}{\sqrt{\varepsilon_2} \cos \Theta_1 + \sqrt{\varepsilon_1} \cos \Theta_2} = \frac{n^2 \cos \Theta_1 - \sqrt{n^2 - \sin^2 \Theta_1}}{n^2 \cos \Theta_1 + \sqrt{n^2 - \sin^2 \Theta_1}}$$

$$T_{\text{TM}} = \frac{2\sqrt{\varepsilon_1} \cos \Theta_1}{\sqrt{\varepsilon_2} \cos \Theta_1 + \sqrt{\varepsilon_1} \cos \Theta_2} = \frac{2n \cos \Theta_1}{n^2 \cos \Theta_1 + \sqrt{n^2 - \sin^2 \Theta_1}}$$

$$\Gamma_{\text{TE}} = \frac{\sqrt{\varepsilon_1} \cos \Theta_1 - \sqrt{\varepsilon_2} \cos \Theta_2}{\sqrt{\varepsilon_1} \cos \Theta_1 + \sqrt{\varepsilon_2} \cos \Theta_2} = \frac{\cos \Theta_1 - \sqrt{n^2 - \sin^2 \Theta_1}}{\cos \Theta_1 + \sqrt{n^2 - \sin^2 \Theta_1}}$$

$$T_{\text{TE}} = \frac{2\sqrt{\varepsilon_1} \cos \Theta_1}{\sqrt{\varepsilon_1} \cos \Theta_1 + \sqrt{\varepsilon_2} \cos \Theta_2} = \frac{2 \cos \Theta_1}{\cos \Theta_1 + \sqrt{n^2 - \sin^2 \Theta_1}}$$

$$\Gamma_{\text{TM}} = 0 \quad \Leftrightarrow \quad \tan \Theta_B = \sqrt{\frac{\varepsilon_2}{\varepsilon_1}} = \frac{n_2}{n_1} = n$$

$$\frac{2\pi}{\lambda_1} z_{0m} \cos \Theta_m = m\pi \quad \Rightarrow \quad d = -z_{0m} = \frac{\lambda_1 m}{2 \cos \Theta_m} = \frac{m}{2 f \sqrt{\mu_1 \varepsilon_1} \cos \Theta_m}$$

$$\lambda_x = \frac{\lambda_1}{\sin \Theta_m}$$

$$\lambda_{\text{H},m} = \frac{\lambda_0}{\sin \Theta_m}$$

$$d = m \frac{\lambda_0}{2}$$

$$f_{\text{G},m} = \frac{m c}{2d}$$

$$\lambda_{\text{G},m} = \frac{c}{f_{\text{G},m}} = \frac{2d}{m}$$

$$\lambda_{\text{H},m} = \frac{\lambda_0}{\sqrt{1 - \left(\frac{m \lambda_0}{2d}\right)^2}}$$

$$\lambda_{\text{H},m} = \frac{\lambda_0}{\sqrt{1 - \left(\frac{\lambda_0}{\lambda_{\text{G},m}}\right)^2}}$$

$$\sin \Theta_m = \frac{\lambda_0}{\lambda_{\text{H},m}} = \sqrt{1 - \left(\frac{m \lambda_0}{2d}\right)^2}$$

Die Oberflächenwelle

$$s_1 = \frac{\sigma_1}{\omega \varepsilon_1} \gg 1$$

$$s_2 = \frac{\sigma_2}{\omega \varepsilon_2} \ll 1$$

$$k_{E2} = \omega \sqrt{\varepsilon_2 \mu_0}$$

$$k_z \approx k_{E2} \left(1 - j \frac{1}{2s_1} \frac{\varepsilon_2}{\varepsilon_1} \right)$$

$$\alpha \approx k_{E2} \frac{1}{2s_1} \frac{\varepsilon_2}{\varepsilon_1} = k_{E2} \left(\frac{\mathbb{R}_1}{\mathbb{R}_2} \right)^2 = \frac{\beta}{2} \frac{1}{s_1} \frac{\varepsilon_2}{\varepsilon_1}$$

$$\beta \approx k_{E2} = \omega \sqrt{\varepsilon_2 \mu_0}$$

$$k_{x1} \approx \sqrt{\frac{\omega \mu_0 \sigma_1}{2}} (-1 + j)$$

$$k_{x2} \approx \omega \varepsilon_2 \sqrt{\frac{\omega \mu_0}{2\sigma_1}} (1 - j) = \omega \varepsilon_2 \eta_1$$

$$\frac{k_{x2}}{k_{x1}} \approx -\frac{\omega \varepsilon_2}{\sigma_1}$$

$$E_{x1} = k_{E2} d_1 \frac{1 - \frac{j\varepsilon_2}{2s_1\varepsilon_1}}{-1 + j} A_1 e^{jk_{x1}x} e^{-jk_z z}$$

$$E_{x1} = -E_{z1} \sqrt{\frac{\omega \varepsilon_2}{2\sigma_1}} (1 + j)$$

$$E_{x2} = -\frac{1}{1 - j} E_{z2} \left(\sqrt{\frac{2\sigma_1}{\omega \varepsilon_2}} - j \sqrt{\frac{\omega \varepsilon_2}{2\sigma_1}} \right)$$

$$Z_W = \frac{E_x}{H_y}$$

$$Z_{W2} = \frac{k_z}{\omega \delta_2} = \frac{k_{E2} \left(1 - j \frac{1}{2s_1} \frac{\varepsilon_2}{\varepsilon_1} \right)}{\omega \varepsilon_2 (1 - js_2)} \approx \eta_{E2} \left(1 + j \frac{s_2}{2} \right)$$

$$Z_{W1} = \frac{k_z}{\omega \delta_1}$$

$$\begin{aligned}
I_z &= \int_{\Sigma} \vec{S}_1 \cdot d\vec{F} = \sigma_1 \int_{x=0}^{\infty} \int_{y=0}^b E_{z1} dx dy \\
&= \sigma_1 A_1 b e^{-jk_z z} \int_{x=0}^{\infty} e^{jk_{x1} x} dx \\
&= j \frac{\sigma_1 A_1 b}{k_{x1}} e^{-jk_z z}
\end{aligned}$$

$$dU_z = I_z dZ$$

$$dP = \frac{1}{2} |I_z|^2 dZ$$

$$\vec{T} = \frac{1}{2} \vec{E} \times \vec{H}^* = \frac{1}{2} \begin{bmatrix} -E_z H_y^* \\ 0 \\ E_x H_y^* \end{bmatrix}$$

$$T_{x0} = \frac{1}{2} \left(-E_{z0} H_{y0}^* \right) = -\frac{1}{2} \frac{\omega \delta_1^*}{k_{x1}^*} |A_1|^2$$

$$dP = T_{x0} b dz$$

$$T_{x0} b dz = \frac{1}{2} |I_z|^2 dZ \quad \Rightarrow \quad dZ = -\frac{\omega \delta_1^* k_{x1}^2}{\sigma_1^2} \frac{dz}{b}$$

$$dZ \approx \eta_1 \frac{dz}{b}$$

$$dZ = d\mathbb{R} + j d\mathbb{X}, \quad d\mathbb{R} = \frac{dz}{b} \mathbb{R}_1, \quad d\mathbb{X} = \frac{dz}{b} \mathbb{X}_1$$

$$dP_W = T_W b dz = \frac{1}{2} |I_z|^2 d\mathbb{R}$$

$$I_z = -b H_{y1}(0)$$

$$dP_W = \frac{1}{2} |H_{y1}(0)|^2 b \mathbb{R}_1 dz \quad \text{bzw.} \quad \frac{dP_W}{dz} = \frac{1}{2} |H_{y1}(0)|^2 b \mathbb{R}_1$$

$$p = \frac{1}{b} \frac{dP_W}{dz} = \frac{1}{2} |H_{\text{tang}}(0)|^2 \mathbb{R}_1$$

$$\mathbb{R}_1 = \frac{1}{\sigma_1 d_1} = \mathbb{R}_{\square} \quad (\text{lies: R square})$$

$$R = \frac{l}{\sigma A}$$

$$R = \int dR = \int_0^l \frac{\mathbb{R}_{\square}}{b} dz = \frac{1}{\sigma_1 d_1} \frac{l}{b} \propto \sqrt{\omega}$$

$$R = \frac{l}{2\pi a} \sqrt{\frac{\omega \mu}{2\sigma_1}}, \quad X = \frac{l}{2\pi a} \sqrt{\frac{\omega \mu}{2\sigma_1}}$$

$$\frac{R}{R_0} = \frac{X}{X_0} = \frac{a}{2} \sqrt{\frac{\omega \mu \sigma_1}{2}} = \frac{a}{2d_1} \propto \sqrt{\omega} \gg 1$$

Resonatoren

$$\lambda_{G,m,n} = \frac{1}{\sqrt{\left(\frac{m}{2a}\right)^2 + \left(\frac{n}{2b}\right)^2}}$$

$$\lambda_H = \frac{\lambda}{\sqrt{1 - \left(\frac{\lambda}{\lambda_G}\right)^2}}$$

$$v_P = \frac{c}{\sqrt{1 - \left(\frac{\lambda}{\lambda_G}\right)^2}}$$

$$v_G = c\sqrt{1 - \left(\frac{\lambda}{\lambda_G}\right)^2}$$

$$\kappa^2 = \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 \equiv \omega^2\varepsilon\mu - k_z^2$$

$$\begin{aligned} P &= \int \operatorname{Re}\{\vec{T}\} \cdot d\vec{F} = \int T_z dx dy = -\frac{1}{2} \int_0^a \int_0^b E_y H_x^* dx dy = \frac{\omega k_z \mu}{2} \left(\frac{aA}{\pi}\right)^2 b \int_0^a \sin^2\left(\frac{\pi}{a}x\right) dx \\ &= \frac{\omega k_z \mu}{4} ab \left(\frac{aA}{\pi}\right)^2 \end{aligned}$$

$$-dP = \frac{1}{2} |H_{\text{tang}}|^2 \mathbb{R}_M dF$$

$$\begin{aligned} -\frac{\partial}{\partial z} P(z) &= \frac{1}{2} \mathbb{R}_M \left(2 \int_0^a \left[|H_x|^2 + |H_z|^2 \right]_{y=0} dx + 2 \int_0^b \left[\underbrace{|H_y|^2}_0 + |H_z|^2 \right]_{x=0} dy \right) \\ &= \mathbb{R}_M A^2 \left(\left(\frac{k_z a}{\pi}\right)^2 \int_0^a \sin^2\left(\frac{\pi}{a}x\right) dx + \int_0^a \cos^2\left(\frac{\pi}{a}x\right) dx + \int_0^b dy \right) \\ &= A^2 \mathbb{R}_M \left(\frac{a}{2} \left(1 + \left(\frac{2a}{\lambda_H}\right)^2 \right) + b \right) \end{aligned}$$

$$\alpha = \frac{\pi}{\omega\mu} \mathbb{R}_M \frac{\lambda_H}{a^3 b} \left(\frac{a}{2} \left(1 + \left(\frac{2a}{\lambda_H}\right)^2 \right) + b \right)$$

$$c = p \frac{\lambda_H}{2}, \quad \text{bzw.} \quad k_z = \frac{2\pi}{\lambda_H} = \frac{p\pi}{c}$$

$$\left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 + \left(\frac{p\pi}{c}\right)^2 = \omega_{mnp}^2 \varepsilon \mu$$

$$\omega_{mnp} = \pi v \sqrt{\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2 + \left(\frac{p}{c}\right)^2}$$

$$Q_{0,mnp} = \frac{\omega_{mnp} W}{P}$$

$$Q_0 = \frac{2\pi W}{PT} \quad \text{mit} \quad T = \frac{1}{f_{mnp}}$$

$$W = \frac{1}{4} \int_{\tau} (\varepsilon \vec{E} \cdot \vec{E}^* + \mu \vec{H} \cdot \vec{H}^*) d\tau$$

$$P = \frac{1}{2} \Re_{\mathbb{M}} \oint_{\Sigma} \vec{H}_{\text{tang}} \cdot \vec{H}_{\text{tang}}^* dF$$

$$\lambda_{101} = \frac{2ac}{\sqrt{a^2 + c^2}}$$

$$\omega_{101} = \frac{\pi}{\sqrt{\varepsilon\mu}} \frac{\sqrt{a^2 + c^2}}{ac}$$

$$E_y = -2\omega m \frac{a}{\pi} A \sin\left(\frac{\pi}{a}x\right) \sin\left(\frac{\pi}{c}z\right)$$

$$H_x = 2jk_z \frac{a}{\pi} A \sin\left(\frac{\pi}{a}x\right) \cos\left(\frac{\pi}{c}z\right)$$

$$H_z = -2j A \cos\left(\frac{\pi}{a}x\right) \sin\left(\frac{\pi}{c}z\right)$$

$$W_e = W_m = A^2 \mu \frac{a^2 + c^2}{4c^2} abc$$

$$P = A^2 \Re_{\mathbb{M}} \frac{ac(a^2 + c^2) + 2b(a^3 + c^3)}{c^2}$$

$$Q_0 = \frac{\pi\eta}{2\Re_{\mathbb{M}}} \frac{b\sqrt{(a^2 + c^2)^3}}{ac(a^2 + c^2) + 2b(a^3 + c^3)}$$

$$Q_0 = \frac{\pi\eta\sqrt{2}}{6\Re_{\mathbb{M}}}$$

Koaxialleitungen

$$\begin{aligned}\vec{E} &= E_r \vec{e}_r \\ \vec{H} &= H_\varphi \vec{e}_\varphi\end{aligned}$$

$$\frac{\partial}{\partial z} U(z) + Z' I(z) = 0, \quad \frac{\partial}{\partial z} I(z) + Y' U(z) = 0$$

$$\text{mit } Z' = R' + j\omega L', \quad Y' = G' + j\omega C'$$

$$\frac{\partial}{\partial z} U(z) - Y' Z' U(z) = 0, \quad \frac{\partial}{\partial z} I(z) - Y' Z' I(z) = 0$$

$$U(z) = U_v e^{-jk_z z} + U_r e^{+jk_z z}, \quad I(z) = I_v e^{-jk_z z} + I_r e^{+jk_z z}$$

$$U_v = Z_L I_v, \quad U_r = -Z_L I_r$$

$$Z_L = \sqrt{\frac{Z'}{Y'}} \quad \text{bzw.} \quad Z_L = \sqrt{\frac{R' + j\omega L'}{G' + j\omega C'}}$$

$$jk_z = \sqrt{Y' Z'} = \sqrt{(G' + j\omega C')(R' + j\omega L')}$$

$$\frac{R'}{L'} = \frac{G'}{C'}$$

$$v_P = \frac{\omega}{k} = \frac{\omega}{\text{Re}\{k_z\}} \approx \frac{1}{\sqrt{L'C'}}$$

$$L = \frac{1}{I} \int_{\mathcal{A}} \vec{B} \cdot \vec{n}_{\mathcal{A}} \, d\mathcal{A}$$

$$L' = \frac{1}{I} \int_{r_i}^{r_a} \vec{B} \cdot \vec{n}_{\mathcal{A}} \, dr = \frac{1}{I} \int_{r_i}^{r_a} B_\varphi \, dr = \frac{\mu}{I} \int_{r_i}^{r_a} H_\varphi \, dr$$

$$H_\varphi = \frac{I}{2\pi r}$$

$$L' = \frac{\mu}{I} \int_{r_i}^{r_a} \frac{I}{2\pi r} \, dr$$

$$L' = \frac{\mu}{2\pi} \ln \frac{r_a}{r_i}$$

$$C = \frac{Q}{\int_C \vec{E} \cdot \vec{e}_r \, dr}$$

$$\vec{E} = \frac{\tau}{2\pi\epsilon} \frac{\vec{e}_r}{r}$$

$$C' = \frac{\tau}{\int_C \vec{E} \cdot \vec{e}_r \, dr} = \frac{\tau}{\int_{r_i}^{r_a} \frac{\tau}{2\pi\epsilon} \frac{\vec{e}_r}{r} \cdot \vec{e}_r \, dr} = \frac{2\pi\epsilon}{\int_{r_i}^{r_a} \frac{1}{r} \, dr}$$

$$C' = \frac{2\pi\varepsilon}{\ln \frac{r_a}{r_i}}$$

$$Z_{L,\text{verlustlos}} = \frac{\eta}{2\pi} \ln \frac{r_a}{r_i} \quad \text{mit} \quad \eta = \sqrt{\frac{\mu}{\varepsilon}}$$

$$\mathbb{R}_{\square} = \sqrt{\frac{\omega\mu_L}{2\sigma}}$$

$$R' = \frac{R_{\text{innen}} + R_{\text{ausen}}}{l} \approx \frac{\frac{\mathbb{R}_{\square} l}{2\pi r_i} + \frac{\mathbb{R}_{\square} l}{2\pi r_a}}{l} = \frac{\mathbb{R}_{\square}}{2\pi} \left(\frac{1}{r_i} + \frac{1}{r_a} \right)$$

$$R' = \sqrt{\frac{\omega\mu_L}{2\sigma}} \frac{1}{2\pi} \left(\frac{1}{r_i} + \frac{1}{r_a} \right)$$

$$G' = \omega C' \tan \delta_{\varepsilon} = \omega \frac{2\pi\varepsilon}{\ln \frac{r_a}{r_i}} \tan \delta_{\varepsilon}$$

$$jk_z = \gamma = \alpha + j\beta = \sqrt{(G' + j\omega C')(R' + j\omega L')}$$

$$\alpha = \alpha_R + \alpha_G = \underbrace{\left(\frac{R'}{2\sqrt{\frac{L'}{C'}}} \right)}_{(1)} + \underbrace{\left(\frac{G'\sqrt{\frac{L'}{C'}}}{2} \right)}_{(2)} \underbrace{\frac{1}{\cosh \frac{\delta_R - \delta_G}{2}}}_{(3)}$$

$$\text{mit} \quad \sinh \delta_R = \frac{R'}{\omega L'}, \quad \sinh \delta_G = \frac{G'}{\omega C'}$$

$$\alpha_R \approx \frac{R'}{2\sqrt{\frac{L'}{C'}}} = \frac{\mathbb{R}_{\square}}{2\eta r_a} \frac{1 + \frac{r_a}{r_i}}{\ln \frac{r_a}{r_i}}$$

$$Z_{L,\text{min. Dämpfung}} = \frac{\eta_0}{2\pi\sqrt{\varepsilon_r}} \ln \frac{r_a}{r_i} = \frac{77 \Omega}{\sqrt{\varepsilon_r}}$$

$$U_{\text{max}} = E_{\text{max}} r_i \ln \frac{r_a}{r_i} = E_{\text{max}} r_a \frac{\ln \frac{r_a}{r_i}}{\frac{r_a}{r_i}}$$

$$Z_{L,\text{max. Spannungsfest}} = \frac{60 \Omega}{\sqrt{\varepsilon_r}}$$

$$P_{\text{max}} = \frac{U_{\text{max}}^2}{2Z_L} = \frac{\pi E_{\text{max}}^2 r_i^2}{\eta} \ln \frac{r_a}{r_i} = \frac{\pi E_{\text{max}}^2 r_a^2}{\eta} \frac{\ln \frac{r_a}{r_i}}{\left(\frac{r_a}{r_i}\right)^2}$$

$$Z_{L,\text{max. Leistung}} = \frac{30 \Omega}{\sqrt{\varepsilon_r}}$$

$$p_v(z) = -\frac{dP}{dz} = -\frac{d}{dz} P_0 e^{-2\alpha z} = 2\alpha P_0 e^{-2\alpha z} = 2\alpha P(z)$$

$$\text{mit} \quad \alpha = \alpha_R + \alpha_G$$

Dielektrische Wellenleiter

$$\xi = k_{x1}d$$

$$\eta = k_{x2}d$$

$$-\xi \cot \xi = \eta$$

$$\xi^2 + \eta^2 = \omega^2 \mu_0 d^2 (\varepsilon_1 - \varepsilon_2) = V^2 \quad \Rightarrow \quad V = \frac{2\pi d}{\lambda_0} \sqrt{n_1^2 - n_2^2}$$

$$k_{x1,m} = \frac{(2m-1)\pi}{2d}, \quad m = 1, 2, \dots$$

$$\omega_{c,m} = \frac{(2m-1)\pi}{2d\sqrt{\varepsilon_0\mu_0(\varepsilon_{r1} - \varepsilon_{r2})}}$$

Streifenleitungen

$$Z_L \approx \sqrt{\frac{\mu_0}{\varepsilon_0}} \frac{1}{2\pi} \ln \left(\frac{8h}{w} + \frac{w}{4h} \right)$$

$$Z_W = \frac{Z_L}{\sqrt{\varepsilon_{\text{eff}}}}$$

$$\lambda = \frac{\lambda_0}{\sqrt{\varepsilon_{\text{eff}}}}$$

$$\varepsilon_{\text{eff}} = 1 + q(\varepsilon_r - 1)$$

$$f_{c,\text{TEM}} = \frac{c}{4h\sqrt{\varepsilon_r - 1}}$$

$$h_{\text{max}} = \frac{\lambda_0}{4\sqrt{\varepsilon_r - 1}}$$

$$f_{c,\text{QTEM}} = \frac{c}{(2w + 0,8h)\sqrt{\varepsilon_r}}$$

$$\alpha = \alpha_L + \alpha_D$$

$$-\frac{\partial}{\partial z} P(z) = |H_{x0}|^2 \mathbb{R} w,$$

$$\mathbb{R} = \sqrt{\frac{\omega\mu}{2\sigma}},$$

$$\alpha_L = \frac{1}{2P(z)} \sqrt{\frac{\omega\mu}{2\sigma}} w |H_{x0}|^2 = \sqrt{\frac{\omega\mu}{2\sigma}} \frac{1}{\eta h}$$

$$P = \int \vec{P} \cdot d\vec{F} = \int T_{w,z} dx dy = \frac{1}{2} \int E_y H_x^* dx dy = \frac{1}{2\eta} |E_{y0}|^2 h w$$

$$Z_W = \eta \frac{h}{w}.$$

$$\alpha_L = \sqrt{\frac{\omega\mu}{2\sigma}} \frac{1}{Z_W w}.$$

$$\alpha'_L = \alpha_L \left(1 + \frac{2}{\pi} \arctan \left(1, 4 \frac{\Delta}{d_1} \right) \right)$$

$$\alpha_D = k_E \frac{s}{2}, \quad \frac{\varepsilon'}{\varepsilon''} = \tan \Theta = s$$

$$\alpha_D = \frac{\pi}{\lambda} \tan \Theta$$

$$\alpha_D = \frac{\pi}{\lambda} \tan \Theta \left(\frac{\varepsilon_r \varepsilon_{\text{eff}} - 1}{\varepsilon_{\text{eff}} \varepsilon_r - 1} \right)$$

Wellen und Hindernisse

$$\Gamma_{\text{rauh}} = \Gamma_{\text{glatt}} \exp [-2 (k\sigma \cos \Theta_e)^2]$$

$$E/E_0 = 1/2 - \exp(-j\pi/4) [C(v) + jS(v)] / \sqrt{2}$$

$$C(v) = \int_0^v \cos(\pi t^2/2) dt \quad S(v) = \int_0^v \sin(\pi t^2/2) dt$$
$$v = h\sqrt{2/\lambda (1/d_s + 1/d_e)}$$

Antennen

$$\vec{\mathbf{A}}(\vec{r}) = \mu \int_{V'} \frac{\vec{\mathbf{S}}_e(\vec{r}') e^{-jk|\vec{r}-\vec{r}'|}}{4\pi|\vec{r}-\vec{r}'|} dV'$$

$$\vec{\mathbf{A}}(\vec{r}) = \mu \frac{e^{-jkr}}{4\pi r} \int_{V'} \vec{\mathbf{S}}_e(\vec{r}') e^{+jkr' \cos \vartheta} dV' = \mu \frac{e^{-jkr}}{4\pi r} \vec{\mathbf{N}}(\vartheta)$$

$$\begin{aligned} |\vec{r} - \vec{r}'| &= \sqrt{r^2 + r'^2 - 2rr' \cos \vartheta} \\ &= \sqrt{(r - r' \cos \vartheta)^2 + r'^2 \sin^2 \vartheta} \\ &= (r - r' \cos \vartheta) \left[1 + \frac{1}{2} \frac{r'^2 \sin^2 \vartheta}{(r - r' \cos \vartheta)^2} + \dots \right] \end{aligned}$$

$$\Delta\alpha = k\Delta r = \frac{2\pi}{\lambda} \frac{r'^2 \sin^2 \vartheta}{2(r - r' \cos \vartheta)}$$

$$\Delta\alpha_{max} = \frac{\pi}{\lambda} \frac{r'^2}{r}$$

$$\frac{\pi}{2} = \frac{\pi}{\lambda} \frac{D^2}{r_R}$$

$$r_R = \frac{2D^2}{\lambda} (+\lambda)$$

$$\frac{\mathbf{E}_\vartheta(\vartheta, \varphi)}{\mathbf{E}_\vartheta(\vartheta_{max}, \varphi_{max})} = \frac{\mathbf{H}_\varphi(\vartheta, \varphi)}{\mathbf{H}_\varphi(\vartheta_{max}, \varphi_{max})} = f(\vartheta, \varphi)$$

$$\vartheta_{max} = \pi/2 \text{ und}$$

$$\varphi_{max} = \text{beliebig}$$

$$\frac{\mathbf{E}_\vartheta}{\mathbf{E}_\vartheta(\pi/2)} = \frac{\mathbf{H}_\varphi}{\mathbf{H}_\varphi(\pi/2)} = f(\vartheta, \varphi) = \sin \vartheta$$

$$\phi = r^2 \operatorname{Re} \left\{ \vec{\mathbf{T}} \right\} \cdot \vec{e}_r$$

$$\vec{\mathbf{T}} = \frac{1}{2} \vec{\mathbf{E}} \times \vec{\mathbf{H}}^*$$

$$\frac{1}{2} \int_f (\vec{\mathbf{E}} \times \vec{\mathbf{H}}^*) \cdot \vec{e}_r df$$

$$P_r = \frac{1}{2} \text{Re} \left\{ \iint_f \left(\vec{\mathbf{E}} \times \vec{\mathbf{H}}^* \right) \cdot \vec{e}_r df \right\}$$

$$df = r^2 \sin \vartheta d\vartheta d\varphi = r^2 d\Omega$$

$$P_r = \int_{4\pi} \text{Re} \left\{ \vec{\mathbf{T}} \right\} r^2 \cdot \vec{e}_r d\Omega = \int_{4\pi} \phi d\Omega = \phi_{max} \int_{4\pi} \frac{\phi}{\phi_{max}} d\Omega$$

$$f(\vartheta, \varphi) = \frac{\mathbf{E}(\vartheta, \varphi)}{\mathbf{E}(\vartheta_{max}, \varphi_{max})}$$

$$\frac{\phi}{\phi_{max}} = |f(\vartheta, \varphi)|^2$$

$$P_r = \phi_{max} \int_{4\pi} |f(\vartheta, \varphi)|^2 d\Omega = \phi_{max} \Omega_{\ddot{a}}$$

$$\Omega_{\ddot{a}} = \int_0^{2\pi} \int_0^\pi |f(\vartheta, \varphi)|^2 \sin \vartheta d\vartheta d\varphi$$

$$D = \frac{4\pi}{\Omega_{\ddot{a}}} = \frac{4\pi}{\int_0^{2\pi} \int_0^\pi |f(\vartheta, \varphi)|^2 \sin \vartheta d\vartheta d\varphi}$$

$$\frac{P_{\text{LHD}}}{P_{\text{LDUT}}} = \frac{P_{\text{rHD}}}{P_{\text{rDUT}}} e_{\text{DUT}} = \dots$$

$$|\mathbf{E}_{\vartheta HD}| = \frac{\eta |\mathbf{I}| s}{2\lambda r} \sin \vartheta.$$

$$P_{\text{rHD}} = \frac{\pi \eta}{3} \left(\frac{s^2}{\lambda^2} \right) |\mathbf{I}|^2$$

$$|\mathbf{E}_{\vartheta HD}| = \sqrt{\frac{3\eta}{4\pi}} \sqrt{P_{r,HD}} \frac{\sin \vartheta}{r}$$

$$P_{\text{rHD}} = \frac{4\pi r^2}{3\eta} |\mathbf{E}_{\vartheta HD}|^2 \frac{1}{\sin^2 \vartheta}$$

$$\frac{|\mathbf{E}_{\vartheta HD}|}{|\mathbf{E}_{\vartheta HD}|_{max}} = f_{HD}(\vartheta) = \sin \vartheta$$

$$P_{\text{rHD}} = \frac{4\pi r^2}{3\eta} |\mathbf{E}_{\vartheta,HD}|_{max}^2$$

$$\mathbf{E}_\vartheta = \frac{j\eta \mathbf{I}}{2\pi r} e^{-jkr} \mathbf{F}(\vartheta, \varphi)$$

$$\mathbf{H}_\varphi^* = -j \frac{\mathbf{I}^*}{2\pi r} e^{+jkr} \mathbf{F}^*(\vartheta, \varphi)$$

$$P_{\text{rDUT}} = \frac{1}{2} \text{Re} \left\{ \oint_f \left(\vec{\mathbf{E}} \times \vec{\mathbf{H}}^* \right) \cdot \vec{e}_r df \right\} = \frac{1}{2} \int_0^{2\pi} \int_0^\pi \eta \frac{|\mathbf{I}|^2}{4\pi^2 r^2} |\mathbf{F}(\vartheta, \varphi)|^2 r^2 \sin \vartheta d\vartheta d\varphi =$$

$$\begin{aligned}
&= \eta \frac{|\mathbf{I}|^2}{8\pi^2} \int_0^{2\pi} \int_0^\pi |\mathbf{F}(\vartheta, \varphi)|^2 \sin \vartheta d\vartheta d\varphi \\
|\mathbf{E}_\vartheta|_{max} &= \frac{\eta |\mathbf{I}|}{2\pi r} |\mathbf{F}(\vartheta_{max}, \varphi_{max})| \\
\frac{|\mathbf{E}_\vartheta|}{|\mathbf{E}_\vartheta|_{max}} &= \frac{|\mathbf{F}(\vartheta, \varphi)|}{|\mathbf{F}(\vartheta_{max}, \varphi_{max})|} = |f(\vartheta, \varphi)| \\
|\mathbf{F}(\vartheta, \varphi)| &= |f(\vartheta, \varphi)| |\mathbf{F}(\vartheta_{max}, \varphi_{max})| = |f(\vartheta, \varphi)| \frac{2\pi r}{\eta |\mathbf{I}|} |\mathbf{E}_\vartheta|_{max} \\
P_{\text{rDUT}} &= \frac{r^2}{2\eta} |\mathbf{E}_\vartheta|_{max}^2 \int_0^{2\pi} \int_0^\pi |f(\vartheta, \varphi)|^2 \sin \vartheta d\vartheta d\varphi \\
\frac{P_{\text{rHD}}}{P_{\text{rDUT}}} &= \frac{\frac{4\pi r^2}{3\eta} |\mathbf{E}_{\vartheta HD}|_{max}^2}{\frac{r^2}{2\eta} |\mathbf{E}_\vartheta|_{max}^2 \int_0^{2\pi} \int_0^\pi |f(\vartheta, \varphi)|^2 \sin \vartheta d\vartheta d\varphi} \\
G_{REF} &= \frac{P_{\text{LREF}}}{P_{\text{LDUT}}} \cdot \frac{|\mathbf{E}_{\vartheta DUT}|_{max}^2}{|\mathbf{E}_{\vartheta REF}|_{max}^2} \\
G_{HD} &= e_{DUT} \frac{8\pi/3}{\int_0^{2\pi} \int_0^\pi |f(\vartheta, \varphi)|^2 \sin \vartheta d\vartheta d\varphi} \\
G_{HD} &= \frac{P_{\text{LHD}}}{P_{\text{LDUT}}} \cdot \frac{|E_{\vartheta DUT}|_{max}^2}{|E_{\vartheta HD}|_{max}^2} = e_{DUT} \frac{P_{\text{rHD}}}{P_{\text{rDUT}}} \cdot \frac{|E_{\vartheta DUT}|_{max}^2}{|E_{\vartheta HD}|_{max}^2} \\
G_{HD} &= \frac{8\pi/3}{\int_0^{2\pi} \int_0^\pi |f(\vartheta, \varphi)|^2 \sin \vartheta d\vartheta d\varphi} \\
G_{HD} &= \frac{8\pi/3}{\Omega_{\ddot{u}}} = \frac{2}{3} G_{ISO} \\
T_E(r) &= G \frac{P_S}{4\pi r^2} \\
|\mathbf{E}_E| &= \frac{A}{\lambda r} E_0 \\
T_E(r) &= \frac{|\mathbf{E}_E|^2}{2\eta} = \left(\frac{A}{\lambda r} \right)^2 \frac{E_0^2}{2\eta} \\
P_S &= \frac{E_0^2}{2\eta} A \\
G &= 4\pi r^2 \frac{T_E(r)}{P_S} = 4\pi \frac{A}{\lambda^2} \\
G_{ISO} &= \frac{4\pi}{\lambda^2} A w \\
P_E &= A T_E
\end{aligned}$$

$$G_{\text{DUT/ISO}} = \frac{EIRP}{P_{\text{LDUT}}} \cdot \frac{|E_{\vartheta_{\text{DUT}}}|_{\text{max}}^2}{|E_{\vartheta_{\text{ISO}}}|_{\text{max}}^2}$$

$$EIRP = P_L G_{\text{ISO}}$$

$$L = ns$$

$$l = \frac{\pi D}{\cos \psi}$$

$$s = l \sin \psi = \pi D \tan \psi$$

$$k_{\text{wendel}} l - k_0 s = 2\pi\nu \quad \nu = 1, 2, 3, \dots$$

$$k_{\text{wendel}} = \frac{\omega}{v}$$

$$\omega \left(\frac{l}{v} - \frac{s}{c_0} \right) = 2\pi\nu \quad \nu = 1, 2, 3, \dots$$

$$\omega = 2\pi \frac{c_0}{\lambda_0} \quad \text{und} \quad l \approx \pi D \approx \lambda_0$$

$$l = (\lambda_0 + s) \frac{v}{c_0}$$

$$\frac{3}{4} \lambda_0 < \lambda < \frac{4}{3} \lambda_0$$

$$\mathbf{P} = \frac{1}{2} |\mathbf{I}|^2 \mathbf{Z}_A$$

$$\vec{\mathbf{T}} = \frac{1}{2} \vec{\mathbf{E}} \times \vec{\mathbf{H}}^*$$

$$\mathbf{T}_r = \frac{1}{2} \mathbf{E}_\vartheta \mathbf{H}_\varphi^*$$

$$\mathbf{T}_\vartheta = -\frac{1}{2} \mathbf{E}_r \mathbf{H}_\varphi^* \approx 0$$

$$\mathbf{T}_\varphi \equiv 0$$

$$|\mathbf{H}_\varphi| = |\mathbf{E}_\vartheta| / \eta$$

$$P_r = \frac{1}{2} \int_{\varphi=0}^{2\pi} \int_{\vartheta=0}^{\pi} \frac{|\mathbf{E}_\vartheta|^2}{\eta} r^2 \sin \vartheta d\vartheta d\varphi$$

$$\mathbf{E}_\vartheta = j\eta \frac{\mathbf{I}s}{2\lambda} \frac{e^{-jkr}}{r} \sin \vartheta$$

$$P_r = \eta \frac{|\mathbf{I}|^2 s^2}{8\lambda^2} 2\pi \int_0^\pi \sin^3 \vartheta d\vartheta$$

$$P_r = \frac{1}{3} \pi \eta \left(\frac{s^2}{\lambda^2} \right) |\mathbf{I}|^2$$

$$R_A = \frac{2}{3} \pi \eta \left(\frac{s^2}{\lambda^2} \right)$$

$$m = \frac{1 + |\rho|}{1 - |\rho|} = \frac{|U_{\text{max}}|}{|U_{\text{min}}|}$$

$$\mathbf{Z}(z) = \frac{\mathbf{U}(z)}{\mathbf{I}(z)}$$

$$Q = \frac{\omega}{2R_A} \left(\frac{\partial X_A}{\partial \omega} \right) \Big|_{\omega=\omega_0} \quad \text{mit} \quad \mathbf{Z}_A = R_A + jX_A$$

$$\Delta\omega = \frac{\omega_0}{Q}$$

$$Q = \frac{\omega}{2G_A} \left(\frac{\partial B_A}{\partial \omega} \right) \Big|_{\omega=\omega_0} \quad \text{mit} \quad \mathbf{Y}_A = G_A + jB_A$$

$$r = r_0 \exp(a\psi)$$

$$\frac{P_{S1}}{P_{E2}} = \frac{P_{S2}}{P_{E1}}$$

$$G(\vartheta, \varphi) = \frac{P_{LREF}}{P_{LDUT}} \cdot \frac{|E_{\vartheta DUT}(\vartheta, \varphi)|^2}{|E_{\vartheta REF}(\vartheta, \varphi)|^2} =$$

$$= \frac{P_{LREF}}{P_{LDUT}} \frac{|E_{\vartheta DUT}|_{\max}^2}{|E_{\vartheta REF}|_{\max}^2} \frac{|f_{DUT}(\vartheta, \varphi)|^2}{|f_{REF}(\vartheta, \varphi)|^2} =$$

$$= G_{REF} \cdot \frac{|f_{DUT}(\vartheta, \varphi)|^2}{|f_{REF}(\vartheta, \varphi)|^2}$$

$$MEG = \int_{4\pi} G(\vartheta, \varphi) P(\vartheta, \varphi) d\Omega$$

Wellen im freien Raum

$$r \doteq \sqrt{\frac{d\lambda}{4}}$$

$$T_{e,ISO} = \frac{P_s}{4\pi d^2}$$

$$T_e = \frac{P_s G_s}{4\pi d^2}$$

$$P_e = T_e A_e$$

$$P_e = T_e A_e = \frac{P_s G_s}{4\pi d^2} A_e$$

$$A = \frac{\lambda^2}{4\pi} G_{iso}$$

$$P_e = \frac{P_s G_s}{4\pi d^2} \frac{\lambda^2}{4\pi} G_e = P_s \left(\frac{\lambda}{4\pi d} \right)^2 G_s G_e$$

$$P_e = P_s \left(\frac{1}{\lambda d} \right)^2 A_s A_e$$

$$L|_{\text{dB}} = 10 \log \frac{P_s}{P_e}$$

$$P_e|_{\text{dBW}} = P_s|_{\text{dBW}} + G_s|_{\text{dB}} - L_{ISO}|_{\text{dB}} + G_e|_{\text{dB}}$$

$$L_{ISO} = -20 \log \left(\frac{\lambda}{4\pi d} \right)$$

$$L_s = 10 \log \frac{P_s}{P_n} = 10 \cdot \log \frac{P_s}{P_{e,\min}} \frac{P_{e,\min}}{P_n} = L|_{\text{dB}} + SNR_{\min}|_{\text{dB}}$$

$$T_i = \frac{P_s G_s}{4\pi d^2}$$

$$P_e = T_e A_e = \frac{T_i \sigma}{4\pi d^2} A_e = \frac{P_s G_s \sigma}{(4\pi d^2)^2} \frac{\lambda^2}{4\pi} G_e$$

$$\frac{P_e}{P_s} = \sigma G_s^2 \left(\frac{\lambda}{4\pi} \right)^2 \frac{1}{4\pi d^4}$$

$$\sigma = AG = A \frac{4\pi}{\lambda^2} A = 4\pi \frac{A^2}{\lambda^2}$$

Mehrwegeausbreitung

$$\tau_1 = d_1/c, \quad \text{und} \quad \tau_2 = d_2/c$$

$$\mathbf{h}(\tau) = \mathbf{A}_1 \delta(\tau - \tau_1) + \mathbf{A}_2 \delta(\tau - \tau_2)$$

$$\mathbf{H}(j\omega) = \int_0^{\infty} \mathbf{h}(\tau) e^{-j\omega\tau} d\tau = \mathbf{A}_1 e^{-j\omega\tau_1} + \mathbf{A}_2 e^{-j\omega\tau_2}$$

$$|\mathbf{H}(j\omega)| = \sqrt{A_1^2 + A_2^2 + 2A_1A_2 \cos(\omega \cdot \Delta\tau)} \quad \text{mit} \quad \Delta\tau = \tau_2 - \tau_1$$

$$\Delta f_{Notch} = \frac{1}{\Delta\tau}$$

$$\mathbf{H}(j\omega) = |\mathbf{H}(j\omega)| e^{j\phi_H(j\omega)}$$

$$\tau_{Gr} = -\frac{d\phi_H}{d\omega}$$

$$\vec{\mathbf{E}}(\vec{r}) = \vec{\mathbf{E}}_1 e^{-j\vec{k}_1 \vec{r}} + \vec{\mathbf{E}}_2 e^{-j\vec{k}_2 \vec{r}}$$

$$\vec{\mathcal{E}}(t) = \vec{E}_0 \cdot \cos(\omega t - kd)$$

$$\begin{aligned} \vec{\mathcal{E}}(t) &= \vec{E}_0 \cdot \cos(\omega t - k[d_0 + vt]) \\ &= \vec{E}_0 \cdot \cos(t[\omega - kv] - kd_0) \\ &= \vec{E}_0 \cdot \cos\left(t\left[2\pi f - \frac{2\pi}{\lambda}v\right] - kd_0\right) \\ &= \vec{E}_0 \cdot \cos\left(2\pi t\left[f - \frac{v}{\lambda}\right] - kd_0\right) \end{aligned}$$

$$\Delta f_D = -\frac{v}{\lambda} = -f \cdot \frac{v}{c}$$

$$\Delta f_D = -\frac{v}{\lambda} \cos(\gamma) = -f \cdot \frac{v}{c} \cos(\gamma)$$

$$p(E) = \frac{1}{\sigma\sqrt{2 \cdot \pi}} \cdot e^{-\frac{E^2}{2 \cdot \sigma^2}}$$

$$\text{Varianz:} = \overline{E^2} - (\overline{E})^2$$

$$\text{Varianz} = \overline{E^2} = \int_{-\infty}^{\infty} E^2 \cdot p(E) dE = \sigma^2$$

$$\sigma^2 = \overline{Re(\mathbf{E})^2} = P_m$$

$$p(a) = \frac{a}{\sigma^2} \cdot \exp\left[-\frac{a^2}{2\sigma^2}\right]$$

$$\begin{aligned}
& \text{Mittelwert} \quad \bar{a} = \sigma \sqrt{\frac{\pi}{2}} \\
\text{quadrat. Mittelwert} \quad & \overline{a^2} = 2\sigma^2 \\
& \text{Varianz} \quad \overline{a^2} - (\bar{a})^2 = 2\sigma^2 - \sigma^2 \frac{\pi}{2} = 0.429\sigma^2 \\
& \text{Medianwert} \quad a_{50} = \sigma \sqrt{2 \cdot \ln 2} = 1.18 \sigma
\end{aligned}$$

$$p(a) = \frac{a}{\sigma^2} \cdot \exp \left[-\frac{a^2 + A^2}{2\sigma^2} \right] \cdot I_0 \left(\frac{aA}{\sigma^2} \right)$$

$$\text{quadrat. Mittelwert} \quad \overline{a^2} = 2\sigma^2 + A^2$$

$$\frac{P_e}{P_r} = G_s \cdot G_e \left(\frac{\lambda}{4\pi d_0} \right)^2 \left(\frac{d_0}{d} \right)^n$$

$$p(F) = \frac{1}{\sigma_F \sqrt{2 \cdot \pi}} \cdot \exp \left[-\frac{(F - M)^2}{2 \cdot \sigma_F^2} \right]$$